

Ocean Bottom Seismometer Technology

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Seismometers have been placed on the ocean bottom for about 45 years, beginning with the work of Ewing and Vine (1938), and their current use to measure signals from earthquakes and explosions constitutes an important research method for seismological studies. Approximately 20 research groups are active in the United Kingdom, France, West Germany, Japan, Canada, and the United States. A review of ocean bottom seismometer (OBS) instrument characteristics and OBS scientific studies may be found in Whitmarsh and Llibre (1984). OBS instrumentation is also important for land seismology. The recording systems that have been developed have been generally more sophisticated than those available for land use, and several modern land seismic recording systems are based on OBS recording system designs.

The instrumentation developed for OBS work was the topic of a meeting held at the University of California, Santa Barbara, in July 1982. This article will discuss the state of the art of OBS Technology, some of the problems remaining to be solved, and some of the solutions proposed and implemented by OBS scientists and engineers. It is not intended as a comprehensive review of existing instrumentation.

The requirements for OBS capsules are similar to those for space satellites. They must be self-contained, have a recovery method, and, usually, a communication system between the ship and the instrument. Reliability is a troublesome problem. Shipboard check-out, repair, and deployment must be streamlined as much as possible since multiple instrument deployments must be accomplished under often adverse conditions.

The typical OBS consists of a buoyant instrument capsule which is held on the bottom by some kind of anchor. It is deployed by dropping it over the side of a ship, whereupon it free-falls to the bottom. The electronics systems which log data, release the anchor, and communicate to the surface acoustically are contained within the pressure case. Both seismometers and hydrophones may be used as sensors. The coupling to the bottom is through the anchor, but schemes have been developed to separate seismometers from the main instrument case in order to improve the coupling to the bottom and reduce the coupling of vibrations between the tape recorder and seismometers. When it is time to retrieve the OBS, the anchor is separated from the buoyant instrument case using an explosive bolt, electrolytically dissolving wire, or mechanical actuator. The instrument case then floats to the surface, where it is retrieved. The following sections will describe each aspect of various OBS in more detail.

ever, the operational advantages of glass spheres are impressive.

Figure 1 shows an OBS using a tube (Mattioli and Solomon, 1977). It uses a 24.1-cm ID tube with a 2.5-cm wall thickness. The external sensor package will be discussed later. Tubes with 15.24 cm ID (6 in.) are more commonly used in physical oceanographic applications and are also used in OBS capsules. Figure 2 shows a design using multiple tubes of this size (Prothero, 1979). Wires connecting the tubes are routed through a common baseplate. The use of tubes for the pressure case has some advantages over spheres. The tube length is variable so that space can be made for future upgrades without a complete redesign of the package; a sphere is much more difficult to enlarge. Tubes with flat endraps provide good surfaces for hydrophones and test connectors, and the interior electronics can be removed more easily for checkout. They are also much less expensive than spheres. The sphere cases are more difficult to disassemble, since the hemispheres are heavy and difficult to hold on to. Handles are usually not installed on spheres, to reduce corrosion at the attachment points. Portable shipboard labs have been specially designed to make this less difficult (Prothero, 1976). A spherical design has a major advantage, however: External flotation is not needed, and this will make it easier to avoid vibrational modes which will distort the signal to be measured. Also, larger components such as sensors and recorders will fit into the sphere but may not fit into the smaller tube instruments.

Acoustic Transponders and Communication

For accurate location of capsules and communication of diagnostic information between the deployed OBS and a surface ship, an acoustic communication system is very useful. The use of acoustic communication was pioneered for free-drop capsules by Snelgrove (1968). Since then, they are commonly incorporated in OBS capsules (e.g., Prothero, 1974; Koelsch and Purdy, 1979). Acoustic communication allows the location of the instrument to be determined to an accuracy of several meters relative to the ship's position. Inversion techniques for optically locating an array of instruments relative to a ship receiving satellite navigation information have been developed (see Crayton and Dorman, 1982). Absolute instrument locations can be determined to 20-30 m by this technique. Flexible instrument recovery times can save expensive ship time, and allow nonfunctioning instruments to be recovered and redeployed. Simple, manually decodable diagnostic codes allow status information such as ground noise level, tape consumption, and number of triggers to be determined before the instrument is left for a long experiment. Prothero (1979) also uses the acoustic system to determine in situ OBS clock corrections accurate to several microseconds.

Commercial acoustic systems in use by various groups are manufactured by Sonotek Corp. (Prothero, 1979; Prothero, 1974), A.M.F. (Koelsch and Purdy 1979; Koelsch et al., 1982), Benihos Corp. (Amber and Davis, 1981), an InterOcean Corp. rebuild (Moore et al., 1981), and are homebuilt (Tucker, 1969). A new, self-contained acoustic release and transponder of extremely small size (12-cm diameter by 51-cm length) was described by H. Murakami (Naguma et al., 1981). It uses frequency modulation between two carrier frequencies of 11.0 and 10.5 kHz to encode the commands and has successfully been used in direct distances up to 8 km from the surface ship.

Data Logging Systems

The design of OBS data recording electronics has been dominated by the dynamic range and storage requirements, which are severe for seismic data. A typical earthquake experiment with an OBS might require a bandwidth of 50 Hz and a recording time of 1 month. For digital data, this would require more than 2.5×10^6 samples for each component recorded. Analog tape recorders have been built which run very slowly and record for 1 month on large reels (e.g., Johnson, R. V., et al., 1977). An important limitation of analog recording is the dynamic range, which is less than 40 dB in the direct write mode. Schemes where various gain channels are employed improve the situation, but the fundamental dynamic range problem exists.

Earthquake experiments place the most stringent requirements on dynamic range of the recording system. If magnitude 0 to 8 earthquakes are to be recorded without saturation, a range of more than 6 orders of magnitude must be recorded. However, a particular event can be adequately recorded using just 12 bits (1:4096 resolution) of data as long as the peak signal is on-scale. Gain-ranging amplifiers provide a solution to this problem. D. Koelsch (Figure 3) reported on a new ocean bottom hydrophone capsule which implements gain ranging in five 12 dB gain

steps (Koelsch et al., 1982). The block diagram shows that the system includes an RCA COSMAC 1802 microprocessor for system control and a DG-300 cartridge tape recorder with 17.3 Mb (megabytes; 1 byte = 8 bits) of data capacity. This system is capable of sampling to 1500 Hz with a 12-bit A-D converter, and to 8500 Hz with an 8-bit A-D. It stores data in a 53,248-byte semiconductor buffer before it writes it to the tape recorder. Capacity for future expansion is provided by using dual port memory and saving space for an NSC 8000 (low-power Z-80 equivalent) microprocessor. Timing is provided by an oven-controlled crystal oscillator accurate to 1 part in 10^6 . A lithium battery pack supplies enough power in the existing pressure case for a 21-day deployment.

This system was designed with the ability to perform high-resolution, high-frequency array studies of shallow structures using controlled sources. Particularly noteworthy is its use of a commercial cartridge recorder. This is a great advantage because the tape recorder is usually one of the components difficult to build and keep running. The only problem with the cartridge recorder is its size, which in the standard configuration will not fit into a 15.24-cm ID pressure tube. Another consideration with a cartridge recorder is that mechanical vibration associated with the high tape speed will most likely shake the seismometer. This means that a semiconductor buffer which can hold the entire event of interest will be necessary, or contamination of the data must be accepted.

Prothero and Schorler (1981) described modifications to the UCSB microprocessor OBS (Prothero, 1979) to optimize it for the recording of teleseismic. A block diagram of the electronics system is shown in Figure 4. Three-component, digital-level seismometers are amplified through filters and a gain-ranging amplifier with three 18-dB gain steps. The gain is reduced by a hardware threshold detector and reset to its maximum value by computer command. This enables gain changes to follow the signal or to be left constant throughout the duration of the event. The system is controlled by an IMB100 12-bit microprocessor, which executes the instruction set of the PDP-8 microcomputer. Recording is done on a Braunauer cassette recorder with capacity of 1.8 Mb on a C30 cassette. The cassette recorder has the disadvantage of low data capacity, but it is very quiet and does not noticeably shake the seismometers when it runs. All triggering, gain setting, acoustic

diagnostics, and data acquisition are controlled by the microprocessor. Modifications to the original microprocessor instrument to allow for teleseismic recording include adding a third tube, changing the seismometers, amplifiers, anti-alias filters, and some new software. The rather minimal hardware changes needed to produce this significant change in function of the instrument attest to the flexibility of a microprocessor-based data logging system. The entire triggering system (including triggering filters) is implemented in software, so the system is very flexible. The response of the 1-Hz Mark Products L4-C seismometers is boosted at low frequencies using a filter with a gain of 100 higher at 20 s periods than at 1 s periods, so useful response to periods as low as 30 s is achieved. The power consumption is low enough to consider deployments as long as 1 year.

The Intersil IM6100 microprocessor is also used by the group at Scripps Institute of Oceanography (Moore et al., 1981). Functionally, it is very similar to the unit of Prothero (1979). It incorporates three-component, 1-Hz sensors and a hydrophone sensor. A modified Uher tape recorder provides high data capacity and is contained in a spherical pressure container, as shown in Figure 1.

At the July 1982 meeting D. Bilbee reported on a new digital instrument using an RCA COSMAC 1802 microprocessor. It has a hydrophone for a sensor and was designed primarily to accurately record the source-time function of large explosive sources used in refraction studies. Digital data are recorded on the same recorder that the Oregon State University group previously used for analog recording (Johnson, S. H., et al., 1977).

C. Young reported on an interesting seismic data recording system (Young, 1982). He designed a seismic data recording system for land deployment that could be constructed for less than \$500. He chose a CDEC chip for the A-D, which encodes the input data with an 8-bit logarithmic code. A Motorola 6805 microprocessor is used to control the gain-ranging, triggering, and recording logic. Recording is done on an inexpensive analog recorder. Tests of the data reconstruction algorithm with real data showed that the signal in the time domain could not be distinguished visually from the original signal. When travel time and waveform synthesis are the primary data interpretation techniques

Article (cont. on p. 114)

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Meteorology

UTLS Chemical Composition and Chemical Interactions
NEAR PROFILES OF TRACE REACTIVE SPECIES IN THE DEVELOPING MARINE SURFACE LAYER
A.M. Thompson and D.H. Llewellyn (National Center for Atmospheric Research, P.O. Box 3000, Boulder, Colorado 80507)

We have investigated several aspects of trace gas photochemistry in the marine boundary layer using a fluorescence transport-laminate cell with one-dimensional diffraction. The photochemical scheme to the model (Thompson and Llewellyn, 1982) is represented by a conventional complement of reactions involving O_3 , H_2O , and various organic species. Boundary conditions are assigned which give for surface mixing ratios of O_3 and SO_2 (Poulsen et al., 1980; McFarland et al., 1979) dependent on the distance from the surface. All other species are assumed to be constant in the surface layer. Diffusion coefficients in the rest of the convective layer (the mixed layer) are taken from Lach and Moran (1978). The surface is assumed to be the tropical ocean with a steady-state mixed layer.

In the simulations described here particular attention has been given to the distribution of O_3 and SO_2 and the SO_2 - SO_3 photochemical state in the surface boundary layer. Calculated profiles of SO_2 , SO_3 , and SO_2 and SO_3 in the surface layer. When the ocean is assumed to be a source of SO_2 , mixing ratios on the order of a few ppt can be supported by an input of SO_2 of 10^{-10} mol $m^{-2} s^{-1}$. If a surface input of SO_2 is not assumed, SO_2 levels are much lower. This is consistent with observations in the tropical Pacific (McFarland et al., 1979; Lach et al., 1980) and suggests that SO_2 input may be significant in the local budget of SO_2 in certain remote marine environments.

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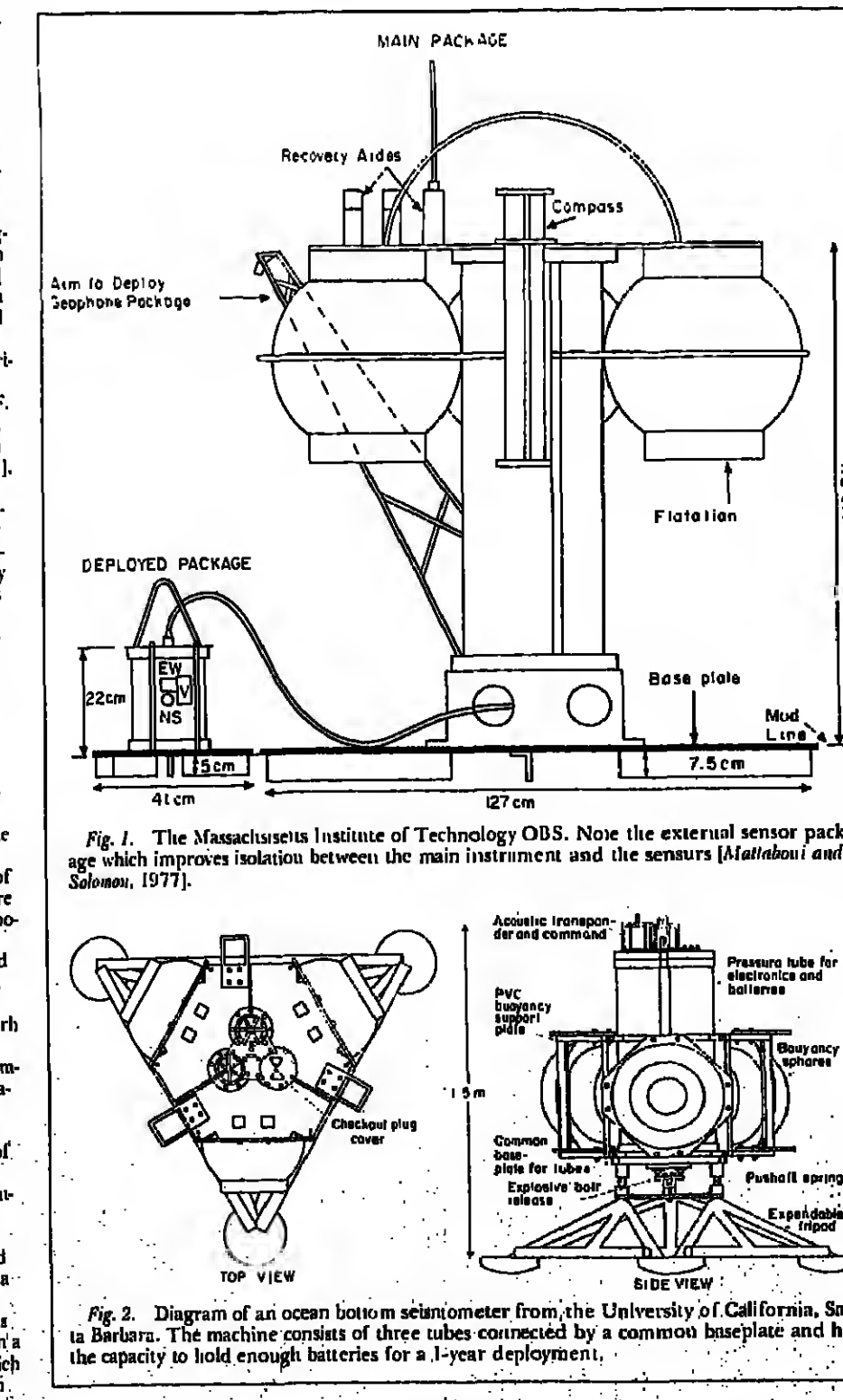


Fig. 1. The Massachusetts Institute of Technology OBS. Note the external sensor package which improves isolation between the main instrument and the sensors (Mattioli and Solomon, 1977).

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this system should be quite adequate and offer a good deal of economy. The system was designed for experiments where a rather few recordings with a great number of stations is needed. It has applications for OBS (probably with greater recording capacity) where very inexpensive instruments might be useful.

Time recorders have been one of the troublesome components of OBS systems. Digital recorders have been used for years by the National Aeronautics and Space Administration for satellite data recording and playback. These are much too expensive for OBS capsules given their funding resources available. OBS engineers have used modified, commercially available analog recorders with good success. *Problems* (1974) used an unmodified Sony TC200B recorder to record approximately 2.5 Mh of digital data. A similar recorder (Uher 5" reel-to-reel) has been modified by R. Moore of Scripps Institution of Oceanography to record 30 Mh. Unfortunately, the Uher is mechanically noisy and large buffer memories are needed to obtain the desired recording results. The Sony TC200B

uncontaminated records. The *Seislog* was quieter but is no longer available. *Aerodisk II*, [1478] have developed a digital tape recorder capable of recording continuously for 150 hours. This *Microdisk* is approximately 7 Mls of capacity. *Magnetograph Systems* [1977] have constructed a standard format, nine-track recorder which stores 10 Mlb. *Minor* has recently completed a prototype of a reel-to-reel recorder with 10 Mlb data capacity. Several commercial options are available. *Korner* [1982] has successfully incorporated a Quantex cartridge recorder in an OBS package. This stores 17 Mlb and uses a 300-ft. (9 m) cartridge tape system. A 673-Mb cartridge recorder is manufactured by 3-M Corporation (HCD-75). These recorders all require a good deal of power and start and stop quickly, so they would be expected to cause quite a bit of vibrational noise. Their power can be reduced between recording periods, so even though they are high-power devices the total energy to write a tape may be small. The Quantex requires 0.5 A at 8 volts. The high vibration expected will require large buffers for the data so that the recorder need not be turned on during the event being sampled; new, large-capacity CMOS memory chips make this feasible.

Since data storage is a major problem for OBS capsules, it is natural to evaluate methods of data compression for this application. The most commonly used method of data compression is event-triggering. This system was first successfully used for OBS capsules by *Frederick (1974)* and *Ambler and Solomon (1974)*. These instruments used an analog trigger which compares a short-term average (STA) of the background noise to a long-term average (LTA). When the STA/LTA ratio drops in more than 8, the recorder turns on for 8 seconds. Recording of the event is set is assured by a digital relay line between the recorder and the analog-to-digital converter (A-D). The recorder time is increased (during an event) for each new trigger so that long events are fully recorded. No micro-earthquake trigger algorithms follow approximately the same principle. Event duration is included in the trigger criterion, which can significantly reduce triggering due to impulsive shocks often caused by biological activity in shallow water. Again, the advantages of microprocessor systems is that these trigger computations can be carried out in software, and may be easily changed and optimized.

Teleseismic triggering algorithms for small computers have been reported by Goforth and Herrin [1981], Prothro and Scharner [1981], Evans and Allen [1983], and Murdoch and Hutt [1983]. The algorithm developed by Goforth and Herrin uses Walsh transforms [Shueks, 1969] to dynamically prewhiten the noise spectrum and examine the frequency content of the signals. These algorithms all use the fact that teleseisms have low-frequency energy, very little high-frequency energy, and while microearthquakes have both high and high frequency energy. The problem is that even though they are implemented on small computers they are still somewhat complex for a full software implementation. Evans and Allen use hard-wire hard-pass filters to determine frequency content of the signal. Prothro and Scharner [1981] reported on a similar triggering algorithm using easily implementable digital filters requiring only shifts (divides in the digital domain) and additions. The software and their cutoff frequencies can be easily changed.

Figure 5 shows a block diagram of this system. It is similar in concept to that reported by Evans and Allen [1983], but does not have many of the special case conditions optimized for larval recording (see also Prothero, 1980). The signal is first hi-passed to eliminate energy from the increasing low frequency noise of the ocean environment. Then the signal is hi-passed by two filters in parallel, with cutoff frequencies of approximately 1 and 4 Hz. The outputs of the two hi-pass filters are compared and only signals with low-frequency components which are deficient in high-frequency components are considered. This has

proven to be extremely efficient at eliminating false triggers. In fact, when the OIS was tested for 1 month in the basement of the geology department at the University of California, Santa Barbara (UCSB) no false triggers were observed, yet all telescisms which were observed on the SCARLETT array stations near UCSB (with sufficient *P*-wave amplitude) were recorded. During deep-ocean deployments the system proved to be equally robust in discriminating against noise. It is anticipated that increasing the trigger sensitivity will result in increased false triggers, however.

The full review of the possibilities for data compression for seismic recording was presented at the July 1982 meeting by A. Gersho, UCSB department of electrical engineering. He summarized data compression techniques used in speech processing and commented on their possible application to OBS data compression. Some work has also been done on this by *Ler and l'arrigando* (1982) and *Wood* (1974). There are three factors to consider in data compression: (1) fidelity, (2) complexity of the algorithm, and (3) compressed bit rate.

The most basic technique of data compression consists of adjusting the sampling to optimize for the expected signals of interest. All OBS groups do this in some form or another. A more generally useful implementation of this technique would add the capability of monitoring the signal and adjusting the sampling rate and dynamic range of the anti-alias filters and decimation according. Another of the oversampling optimizations in wide use is event triggering. Further compression can be achieved by reducing the number of bits chosen to represent the data. OBS engineers have usually used 12-bit linear digitization in the past, but an 8-bit logarithmic encoding scheme which shows promise has been studied by C. Tsong [1982]. The second factor, according to Tsong, is critical for OBS systems: the implementation of the LSS. Chips have been developed for speech processing, but it remains to be seen whether or not they will be useful for seismic data logging purposes.

Two less common compression schemes of immediate interest are "delta modulation" and "differential coding." Delta modulation is a 1-bit method which samples the data at high speed and produces a "1" if the signal is larger than the last sample, or a "0" if the signal is smaller.

for each sample (for decoding) will reduce the improvement somewhat. This scheme would be straightforward to implement on a microprocessor-based system and the signal fidelity would remain unchanged. Compression by a factor of 2 is estimated for this, but clearer coding could probably improve it further.

Other schemes for data compression are subband coding and transform coding. Subband coding consists of band-pass filtering the signal, transforming the filter outputs to low frequencies, then sampling each x transformed output at a reduced rate. Transform coding involves transforming the data by some method (e.g., fast Fourier transforms or Walsh transforms), eliminating coefficients with low amplitude, and storing the remainder. This method is discussed in detail for seismic reflection data by Lloyd [1974]. It obtains a data compression of 28:1 with a fidelity of about 85%. This would probably be unacceptable to most OBS users. Table 1 is a summary of the compression ratios achievable from the various techniques, as presented by Gersho at the OBS technology conference. These assume that a signal-to-noise ratio of 30 dB is required, but the range of a 12-bit A-D is needed. The actual numbers are based on speech processing needs and would need some modification, as well as testing on actual data, for OBS applications.

It would appear that adaptive delta modulation and difference coding would be the easiest to implement in existing systems. Sideband or transform coding may require more computing power than existing microprocessor systems have to spare, so specially dedicated or more powerful processors could be needed. Clearly, there is a large potential payoff in the use of data compression algorithms, and important work remains to be done on this topic.

OBS coupling has received quite a bit of attention recently. OBS intercomparison experiments have shown that identical input signals may be recorded quite differently by different instruments. At the July 1982 conference G. Sutton summarized the results of the Lopez Island intercomparison test (Sutton *et al.*, 1980) and what we now know about OBS coupling. The following list is a summary of possible sources of signal distortion or noise that should be considered in OBS experiment design.

- A. Noise sources with geophysical origin
 - 1. Microseismic amplification
 - 2. Ocean current-induced noise
- 8. Signal-induced noise
 - 1. Distortion from irregular boundaries at sediment-rock interface
 - 2. Complicated reflectious and conversions in the sediment layer
- C. Signal distortions
 - 1. OBS coupling effects, including viscous drag, differential motion between

- 2. Water sediment differential motion, which acts as the response to horizontal inputs
- 3. Rounding due to unstable working of instrument on bottom with small scale regularities
- 4. Vertical to horizontal coupling
- 5. Tilting induced by horizontal motion
- 6. Asymmetries caused by small scale lateral heterogeneities, causing vertical to horizontal coupling

Noise sources with geophysical origin include the microseismic background noise and ocean current-induced noise. Biological activities and cultural noise sources predominate in shallow water and areas of geophysical exsiccation (Djurkovic et al., 1986; Bouch and Tardieu, 1982). Microseismic noise strongly surface weather related (Latham et al., 1968a, 1968b). In addition, the soft bottom sediments can lead to an amplification of microseismic noise. In spite of this, a number of ocean bottom noise measurements show noise levels comparable to those of coastal land sites (Dunham et al., 1974; Pithon et al., 1980; Schoch, 1981). In fact, on hard-rock sites near to ruggedness, the noise at shallow periods is as low as that on much hard installations

A serious potential source of noise is vibrations induced by bottom currents. Centimeter-induced noise has been observed by a number of research teams, in holling *Stellion et al.* [1980], *Thurman et al.* [1981], and *Kasahara et al.* [1980, 1981]. The results of *Kasahara et al.* [1980] suggest that bottom currents may typically exceed 20 cm s⁻¹ and can be a major source of noise on an OBS. *Wimbush and Menck* [1970] show current data taken 1.2 km above the seafloor at 32°N, 124°5'W (6 km west of San Diego) that show variations between 5 cm s⁻¹ and 10 cm s⁻¹ with the dominant frequency being 1 cycles per day. The peak of the "recovered" semidiurnal tide which is the cause of the dominant variation in current speed at this site. The possible rectification must be considered when ground noise is simply correlated with the theoretical tidal currents and test for current-induced noise.

The behavior of the current near the boundary is not simple. A boundary layer (called an Ekman layer) is a transition zone between the current that exists "at great distance" from the boundary and that near the boundary. The mean (current velocity vector) in this transition zone generally increases in distance from the solidbody and can cross the reverse direction. It may be laminar or turbulent and for the case of the ocean bottom, almost always turbulent. For latitudes greater than 30° the critical current speed is 0.1 m s⁻¹ while a typical current speed is 3 cm s⁻¹ (Fjörðvick and Munk, 1972). The dynamics of the boundary layer also depend on the intensity of density stratification. Tide is known about this on the ocean bottom—not even a discussion of the density gradient.

Possible interaction modes are direct interaction on the DMS by the cation, or po-

local ground noise induced by pressure fluctuations acting directly on the bottom by the turbulent boundary layer. The spectrum of the noise which would be generated is unknown but certainly depends on the instrument itself and the current speed. *Kasahara et al.* (1980) have performed experiments to show that the shedding of Karman vortices from the radio beacon antenna causes mechanical oscillations of the OBS at frequencies of 3.2 to 3.7 Hz for current speeds of 18 cm s⁻¹ and 30 cm s⁻¹. The amplitude was large enough to saturate the recording system.

enough to saturate the recording system. This effect was severe in this case because the instrument is rather lightweight and the radio beacon antenna, which was mounted vertically at the top of the instrument, forms a resonant mechanical system. The effect is also due to the current noise observed by *Dunbar et al.* [1981] where the radio beacon antenna is high above the main instrument package and the base-to-height ratio is very low. The experience of other investigators in different parts of the ocean has not been so unambiguous. In the Santa Barbara channel and the deep ocean west of Santa Barbara, where current speeds in excess of 10 cm s⁻¹ would not be expected, *Prothero* [1981] records noise levels that could not be unreasonable for the case of a low ratio. The instrument package is 2-m high but has a large base-to-height ratio, and the radio beacon is inverted beneath the deployed instrument, which would reduce the effect of currents.

Several questions arise regarding the current noise problem. It has been shown that reducing the profile of the instrument by lowering the radio beacon antenna will produce improvements when currents are high. Other investigators have no overwhelmingly obvious problems in this regard. Certainly, some of this is due to the different areas of operation, as well as the differences in package configuration. The use of "burp-out" sensors (which are separate from the main instrument package, so have a lower profile) is relevant to this question and will be discussed below in the section on signal distortions.

Signal-induced noise could affect ocean experiments to a greater degree than land ex-

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Cover. Fountain Square is the historic focal point of Cincinnati, where AGU's 1984 Spring Meeting will be held, May 14-17, 1984. Housing, registration, and travel information and the list of sessions to be held at the meeting begins on p. 122.

periments because of the water layer and the thick layer of low-velocity sediments often overlying more competent, comparatively high-velocity layers. The velocity contrast at the sediment-rock interface may be quite high, leading to severe distortion from trapped and converted waves. Basement topography could also distort waveform amplitudes, depending on the scale of irregularities relative to the wavelength of the seismic wave.

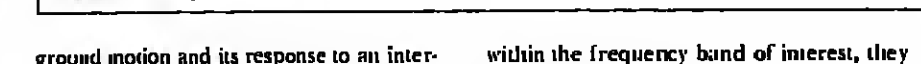
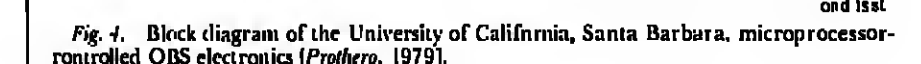
The Lopez Island OBS intercomparison test (Sutton *et al.*, 1980) was conducted to compare the response of existing OBS capsules. What was found was that although some similarities between instruments existed, dramatic differences were also apparent. The first-order coupling effect is due to the elasticity of the bottom which the OBS rests upon (Sutton *et al.*, 1980; Zehle and Prothero, 1981). The system may be described as a damped mass-spring system. The mass is the OBS instrument mass plus an added mass caused by the inertia of the water displaced by the OBS motion. The spring constant is determined by the shear modulus of the soil beneath the instrument footpads, and damping is due to the radiation of seismic energy to infinity. Thus, the system will amplify frequencies at the resonant frequency if the damping is low enough. Figure 6 shows a typical coupling response for various coupling parameters typical of existing OBS capsules. Note that a worst-case amplification at the resonant frequency can be as high as 15 dB. A large bearing radius gives rise to a soft spring and a high coupling resonance (good coupling), while a smaller bearing radius lowers the coupling frequency and increases the need for a coupling correction. A large bearing radius also seems to increase the damping, so that a large bearing radius is preferred.

In addition to the effect of the coupling of the vertical motion, the horizontal signals cause important and unexpected effects. Several of the OBS packages in the Lopez Island OBS intercomparison test had small anchors relative to the size of the instrument capsule, allowing considerable rocking to occur for horizontal ground motion. Even worse (line sight tells us), the sensors were mounted at the end of the pressure case, so considerable vertical motion was also induced by the coupling. This led to a good deal of cross-coupling between horizontal and vertical signals. This was clearly indicated by the fact that cross-coupling for each instrument was proportional to its base-to-height ratio. One solution to this is to build the instrument with a high base-to-height ratio and place the sensors along its dynamic center,

A currently fashionable solution to the coupling problem was introduced by the Hawaiian Institute of Geophysics group [Sutton *et al.*, 1980, 1981; Byrne *et al.*, 1983; Dascherer *et al.*, 1981]. The sensors, informally called "buried" sensors, are able to be deployed separately and at a distance from the main instrument capsule. This technique was very successfully used in ROSE where earthquake data of superb quality were recorded on the MIT instrument [Trehu, 1982]. The instrument was deployed on hard bottom where the actual coupling in the vertical direction would be quite good anyway. However, the separated sensor package was well decoupled from internal modes and noise generated by the large recording package and resulted in extremely low cross-coupling distortion.

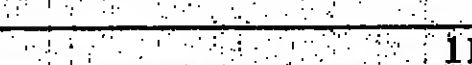
There are pitfalls, however. It can be seen from Figure 8 that a typical OBS instrument package might have a coupling distortion of a factor of 2 to 3 for frequencies at the coupling resonance. For a factor of 2 coupling distortion, the instrument package will be moving at the equivalent of twice the ground motion (at the coupling resonance), or equal to the ground motion relative to the moving bottom. Thus, on sedimented bottoms where the shear velocities are low, an instrument with this characteristic will be pumping energy into Stonely waves, which will travel to the burp-out sensor and shake it in some unpredictable fashion. Since the burp-out sensor cannot be conveniently separated by much more than a meter from the main package, attenuation due to geometric spreading would be minimal. So, it is necessary that a main instrument package also have good coupling. Indeed, tape recorder vibrations and response to extraneous internal modes of vibration might also transfer to the sensor package (but at reduced amplitudes) under some conditions. From a purely engineering viewpoint the external sensor package poses problems with the reliability of the coupling cable and the possibility that the remote sensor might tangle in the anchor or have difficulty disengaging from the bottom when the OBS is released. In spite of this, the method has important advantages, particularly in high currents, and the data quality has been very good. It would be astute, however, to be aware of the potential problems that

Another method of dealing with the coupling problem is by an in situ calibration technique. If the dynamic mass (OBS mass plus added mass from water motion) is constant in frequency and linear over the expected seismic amplitudes, a simple relationship exists between the response of the OBS to



ground motion and its response to an internal mechanical shakers so as to implement an in situ calibration using this important but unknown is the behavior of the dynamic mass up to frequencies of seismic interest, a quantity that appears not to have been studied. Eickemeyer and Prodero reported on results in progress of a study of the dynamic mass of two shapes of oscillating bodies: a sphere and a plate. These shapes have dynamic added mass factors (for the laminar flow approximation) of $0.5M_w$ and $4p_w R^3/3$, where M_w is the mass of the water displaced by the sphere, p_w is the water density, and R is the radius of the sphere [Bathelot, 1967]. In order to test this for sinusoidal motion at seismic frequencies, the shapes were made part of a mass-spring system which could be driven to resonance by shaking. The resonant frequency was between 10 Hz and 30 Hz and compared in and out of water. The change in resonant frequency is related to the mass change. For a 13-cm diameter sphere and a 25-cm diameter

within the frequency band of interest, they could distort the response to ground motion. Benthos glass spheres, which are used on a number of OBS, give cause for concern. It is extremely difficult to attach them rigidly to anything since they have flexible polyethylene protection covers through which any attachment must be made. In order to minimize cross-coupling, the base must be wide compared with the height and the sensor should be located near its center line. The base should have a large surface area, particularly when the OBS will be deployed on sedimented areas. However, a single, large-area contact, such as a plate, will be prone to rocking if deployed on harder bottoms with small scale relief. A tripod anchor gages against the seafloor. However, on soft bottoms, a tripod anchor will respond to horizontal signals in an unacceptably asymmetric manner if the coupling is poor. The best solution might be to use a tripod anchor with large area contact pads. An *in situ* calibration method will give important information on coupling when problems exist.



national water well association C·O·M·I·N·G E·V·E·N·T·S

April 9-11
The Sixth Annual Ground Water Heat Pump Conference
Fawcett Center for Tomorrow
Columbus, Ohio

April 17-19
Design, Installation and Sampling of Ground Water Monitoring Wells: A Short Course
Orlando Marriott Hotel
Orlando, Florida

April 26-28
Water Well Design and Construction: A Short Course for Engineers
Denver Airport Hilton Inn
Denver, Colorado

May 1-4
Ground Water Modeling Without Mathematics
Denver Airport Hilton Inn
Denver, Colorado

May 7-9
The Complete Ground Water and Well Technology Short Course
Hilton Inn North
Columbus, Ohio

May 14-18
Ground Water Investigations of Hazardous Materials Sites: An Intensive Safety Short Course (Two Modules)
Fawcett Center for Tomorrow
Columbus, Ohio

May 23-25
The Fourth National Symposium and Exposition on Aquifer Restoration and Ground Water Monitoring
Fawcett Center for Tomorrow
Columbus, Ohio

June 6-8
Water Well Design and Construction: A Short Course for Engineers
Sheraton Hartford Hotel
Hartford, Connecticut

June 12-13
Northeast Ground Water Exposition
Hartford Civic Center
Hartford, Connecticut

June 22-26
Practical Applications of Ground Water Geochemistry
Banff Springs Hotel
Banff, Alberta, Canada

July 9-11
The Complete Ground Water and Well Technology Short Course
Hilton Inn North
Columbus, Ohio

July 23-24
NWWA Ground Water Technology Division Eastern Regional Technology Conference
Boston Marriott Newton
Boston, Massachusetts

July 25-27
Ground Water and Unsaturated Zone Monitoring and Sampling: A Short Course
Boston Marriott Newton
Boston, Massachusetts

July 30-August 3
Ground Water Investigations of Hazardous Materials Sites: An Intensive Safety Short Course (Two Modules)
Denver Airport Hilton Inn
Denver, Colorado

August 5-7
South Atlantic Well Drillers Jubilee
Myrtle Beach Convention Center
Myrtle Beach, South Carolina

August 7-10
Ground Water Modeling Without Mathematics
Hilton Inn North
Boston, Massachusetts

August 15-17
Conference on Practical Applications of Ground Water Models
Fawcett Center for Tomorrow
Columbus, Ohio

August 21-22
Ground Water Investigations of Hazardous Materials Sites: An Intensive Safety Short Course (Module 1 only)
Thunderbird Hotel
Bloomington, Minnesota

August 27-29
The Impact of Mining on Ground Water
Denver Airport Hilton Inn
Denver, Colorado

September 5-7
Ground Water and Unsaturated Zone Monitoring and Sampling: A Short Course
Hilton Inn North
Columbus, Ohio

September 10-12
The Complete Ground Water and Well Technology Short Course
Hilton Inn North
Columbus, Ohio

September 24-26
International Water Well Exposition
Las Vegas Convention Center
Las Vegas, Nevada

September 26-28
Seventh National Ground Water Quality Symposium
Las Vegas Hilton Inn
Las Vegas, Nevada

October 15-18
Ground Water Modeling Without Mathematics
Sheraton Harbor Island East
San Diego, California

October 23-25
NWWA Western Regional Conference on Ground Water Management
Sheraton Harbor Island East
San Diego, California

October 29-31
NWWA Eastern Regional Conference on Ground Water Management
Sheraton World Hotel
Orlando, Florida

November 5-7
Petroleum Hydrocarbons and Organic Chemicals in Ground Water: Prevention, Detection and Restoration
Guest Quarters West and Intercontinental Hotel
Houston, Texas

November 5-7
The Complete Ground Water and Well Technology Short Course
Hilton Inn North
Columbus, Ohio

November 12-17
International Conference and Exposition on Ground Water Technology
Johannesburg Showgrounds
Johannesburg, South Africa

November 27-29
Water Well Design and Construction: A Short Course for Engineers
Fawcett Center for Tomorrow
Columbus, Ohio

November 27-30
Ground Water Modeling Without Mathematics
Fort Worth Hilton Inn
Fort Worth, Texas

December 3-5
Ground Water and Unsaturated Zone Monitoring and Sampling: A Short Course
Sheraton Airport Inn
Phoenix, Arizona

December 10-12
Ground Water and Unsaturated Zone Monitoring and Sampling: A Short Course
Tampa Marriott Westshore
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NSF's Division of Atmospheric Sciences is seeking high-quality professional applicants as Assistant/Associate Program Director and Program Director for positions which periodically become available. These positions are excepted from the competitive civil service and are filled on a one- or two-year rotational basis under the provisions of NSF's Rotational Program. Typical duties will involve proposal review, advising applicants, budget development, site visits, program development and other administrative duties.

Vacancies to be filled in the Division are in the following areas of interest:

- CLIMATE • FLUID DYNAMICS • METEOROLOGY • AERONAUTICS
- ATMOSPHERIC CHEMISTRY • MAGNETOSPHERIC/IONOSPHERIC PHYSICS • PALEOCLIMATOLOGY • SOLAR PHYSICS
- SOLAR-TERRESTRIAL PHYSICS

Applicants should have a Ph.D. or equivalent experience in the appropriate discipline and, for the Assistant Program Director, 3 to 4 years of successful scientific research experience beyond the Ph.D.; for the Associate Program Director, 4 to 6 years of successful scientific research experience beyond the Ph.D.; and, for the Program Director, 6 to 8 years of successful scientific research experience beyond the Ph.D. is desirable. The per annum salary ranges as follows: Assistant Program Director—\$30,000–\$45,000; Associate Program Director—\$35,000–\$55,000; and, Program Director—\$45,000–\$65,000. Applicants should refer to Announcement EOS/ATM when submitting resumes, including current salary. Send letter of application, resume and names of three references to: Dr. David Schwarzenberg, Department of Geology/Geography, Howard University, Washington, DC 20059. Attn: Catherine Handley. For further information call: 202/557-7840. Hearing impaired individuals should call: TDD 202/557-7492. NSF is an Equal Opportunity Employer.

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Los Alamos National Laboratory
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The Department of Geology/Geography invites applications for a tenure track position in geochemistry at rank of Graduate Associate Professor beginning August 1984. Position involves development of graduate research program at Master's level. Specialization in environmental geochemistry/geochemistry/geochemical geology desired. Send letter of application, resume and names of three references to: Dr. David Schwarzenberg, Department of Geology/Geography, Howard University, Washington, DC 20059.

Senior Applications Chemist. Keyes Corporation is seeking an individual with a strong Analytical Chemistry background, in particular in X-ray Fluorescence, for Applications Laboratory. Three years of experience in full industrial analytical problem solving using XRF is required. Advanced degree in Physical Science or Engineering is preferred. Position requires Applications support in Marketing, Sales and R&D operations. Submit resume to: Mr. Drew Isaacs, Keyes Corporation, 1101 Chest Drive, Foster City, CA 94404. EOE M/F/H/V.

Air Force Geophysics Laboratory Geophysics Scholar Program (1984-1985). The Air Force Geophysics Laboratory (AFGL) and The Southeastern Center for Electrical Engineering Education (SCEE) announce that applications are invited for research appointments during the 1984-1985 year in the Geophysics Scholar Program. This program provides research opportunities of 10 to 18 months duration for selected Engineers and Scientists in pertinent research in residence at the AFGL, Hanscom AFB, near Boston, Massachusetts. Scholars will be selected primarily from such fields as geophysics, atmospheric physics, meteorology, ionospheric physics, applied science, mathematical modeling using computers, and engineering. To be eligible, candidates must have a Ph.D. or equivalent experience in an appropriate technical field. Some appointments may be confirmed prior to August 1984 so early applications are encouraged. All qualified applicants will receive consideration without regard to race, color, religion, sex, or national origin. Application deadline for September appointments: August 1, 1984. For further information and application forms contact: SCEE, 1101 Massachusetts Avenue, St. Cloud, FL 32709. Telephone: (305) 832-5146. SCEE supports Equal Opportunity/Affirmative Action.

STUDENT OPPORTUNITIES

Research Fellowships at the University of Notre Dame. Fellowships in groundwater physics, groundwater chemistry, aquifer processes and hydrogeology are currently available in the Environmental Engineering Program of the Civil Engineering Department. Successful applicants will be awarded annual stipends of up to \$10,000, plus full tuition. For additional information, contact Dr. Aaron A. Jenkins, Department of Civil Engineering, University of Notre Dame, Notre Dame, IN 46556 (219-239-3846).

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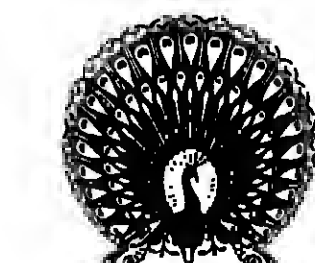
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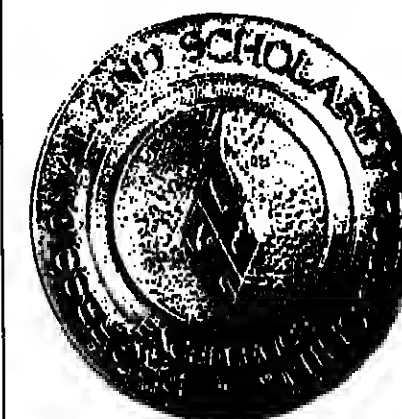
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AGU



Medallion on the plaque awarded to Tectonics by the Association of American Publishers for excellence in journal design and production.

Tectonics Wins AAP Award

AGU's newest journal, *Tectonics*, won the 1983 award for excellence in journal design and production given by the Association of American Publishers, Inc. (AAP), in the eighth annual professional and scholarly publishing awards competition. Edited by John F. Dewey, the bimonthly journal is a joint publication of AGU and the European Geophysical Society. Paul E. Tappin is the European editor and B. C. Burchfiel is the North American editor. The journal is now in its third year of publication.

AAP was especially impressed that AGU met its stated objectives in the production and presentation of the journal. Those objectives included increasing the number of words per page, allowing the publication of more science without significantly increasing the size of the journal, and providing higher quality paper to enhance overall quality and readability of figures.

"In our knowledge, this is the first time the award has been given to an author-produced journal," said John F. Dewey, AGU director of publications, public information, and marketing. "I'm really pleased that a professionally judged contest can give proper recognition to author-produced work."

Under the auspices of the professional and scholarly publishing division of AAP, an independent panel of judges from the publishing industry and from the industrial, medical, and scientific community was convened to judge the more than 320 professional and scholarly journals that were nominated. The works range across the spectrum of science, technology, business, and humanities nominated for the awards competition. The more than 300 publisher members of the professional and scholarly publishing division of AAP account for the majority of book output and sales of professional and scholarly works in the United States.

Mark Rickertsen (H), Michael E. Roberts (V), Eudip S. Salota (T), Suresh Santanam (A), Joachim Schumacher (A), Brad S. Singer (V), Ole Martin Smedstad (O), Joel W. Sparks (V), Scott Starratt (O), Lori Verner (H), Robin J. Weeks (T), Rudolf Widmer (S), Kenneth R. Wilks (T), Jack Whitman (H), David A. Worthington (S), Steven A. Young (T).

Honorable mentions for excellence in journal design and production were awarded to *Winterthur Portfolio*, published by the University of Chicago Press and edited by Ian M. G. Quinby, and to the *Journal of Biomedical Materials Research*, published by John Wiley & Sons and edited by A. Norman Crum.

The award plaque, displayed at AGU headquarters, states, "1983 Excellence in Journal Design and Production Presented to American Geophysical Union for *Tectonics*, Editor-in-Chief: John F. Dewey, Professional and Scholarly Publishing Division, Association of American Publishers."—BTR

AGU Membership Applications

Applications for membership have been received from the following individuals. The letter after the name denotes the proposed primary section affiliation.

Leonard A. Barrie (A), Kenneth Paul Bowman (A), Donald K. Brumfiel (A), Mark Clark, Craig M. DePolo, Robert G. Galsen (G), Boilhu G. Gilbert (T), Mark N. Goliz (H), Dennis J. Gregor, Gary B. Griggs (O), Jafar Hadzadeh (S), Rita K. Hayden, Allan D. Hedou (A), William Brent Hemphills, Charles David Henry (A), George Henry (H).

David Brian Jenkins (A), Kimberly S. Julliz (SS), Teruo Kamezawa, Benny Kullinger (S), Jonathan W. Lott (O), R. J. Luxmoore (H), Gerald L. Maiter (G), Clark Markell (H), Maria Martinez, William D. McCoy (H), C. Thomas McElroy (A), Francisco Medina (V), Masamichi Mitamoto (P), Ronald M. Mrozsky (H), John W. Morse (O).

Brenda L. Norcross (O), Jogen N. Pihl (S), Filippo Rodicci, Michael Retelle (V), Frans J. M. Rietmeijer (A), Ian Rowlandson (H), John Scott (H), Keith Sumner (O), William N. Summers (H), Marjorie L. Summers (V), Kathy Y. Tonneisen (H), Paul Travis, Parker, J. Wigginton (H), James G. Winther (V), Philip C. Woods.

Student Status

Helen J. Anderson (T), Erik Arndberg (V), Shih-Hsin Chung (G), Michael Christie (H), Mahom E. Goss (V), Isabelle Gouze (H), L. Ford Driehuis (O), Robert J. Ellison (H), Jeffrey G. Feehan (T), Benjamin S. Giese, Paul Keith Gilford (T), Mahom Hassan (H), Camie Helin, Andrew J. L. Hogg (V).

Dale R. Isler (T), Craig Jacobson (S), Beth Laband (O), J. H. Lee (H), Steven A. Loomis (H), Douglas M. Mac (A), Kevin A. Maher (T), Japut D. Maniar (V), Ritsuko S. Masumura (S), Gabriele Moehring-Ehrmann (T), Jonathan M. Nelson (A), Scott Nutter, Marino Ostos (T), Lee Pevum (H).

Mark Rickertsen (H), Michael E. Roberts (V), Eudip S. Salota (T), Suresh Santanam (A), Joachim Schumacher (A), Brad S. Singer (V), Ole Martin Smedstad (O), Joel W. Sparks (V), Scott Starratt (O), Lori Verner (H), Robin J. Weeks (T), Rudolf Widmer (S), Kenneth R. Wilks (T), Jack Whitman (H), David A. Worthington (S), Steven A. Young (T).

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Meetings

AGU Spring Meeting

Travel, Housing, and Registration, and Session Summary

The 1984 Spring Meeting of the American Geophysical Union will be held in Cincinnati, Ohio, May 14-17, at the Convention-Exposition Center. The center, located in the heart of the city, is an ideal meeting site; a skywalk system links the Convention-Exposition Center with major downtown hotels, restaurants, and shops. Cincinnati is easily reached by three major highways and the Greater Cincinnati International Airport (only 15 minutes from downtown).

Registration

Everyone who attends the meeting must register. Pre-registration received by April 20 saves you time and money. The fee will be refunded to you if AGU receives written notice of cancellation by May 7. Registration rates are as follows:

	Pre-registration	After April 20
Member	\$70	\$85
Student Member*	\$30	\$45
Retired Senior Member**	\$31	\$45
Nonmember	\$85	\$110
Student Nonmember	\$40	\$55

*Student fee has been rolled back to 1982 rates.

**Age 65 or over and retired from full-time employment.

Registration for 1 day is available at one-half the above rates, either in advance or at the meeting. Members of the American Society of Surveying and Mapping, the American Meteorological Society, the American Society of Photogrammetry, the Canadian Geophysical Union, the European Geophysical Union, and the Union Geofisica Mexicana may register at the AGU member rates.

If you are not a member of AGU and you register at the full meeting rate, the difference between member (or student member) registration and nonmember registration will be applied in AGU dues if a completed membership application is received at AGU by July 9, 1984.

To preregister, fill out the registration form and return it with your payment to AGU by April 20. Preregistrants should pick up their registration material at the registration desk located in the Convention-Exposition Center. Your receipt will be included with your preregistration material. Registration hours are 8 A.M. to 4 P.M., Monday through Thursday. On Sunday, May 13, you may register from 5:30 P.M. to 7:30 P.M.

Hotel Accommodations

Blocks of rooms are being held at the Clarion Hotel (formerly Stouffer's) and at the Netherland Plaza for those attending the Spring Meeting. The Clarion (\$55 single, \$85 double) is immediately adjacent to the Convention-Exposition Center. The Netherland Plaza (\$50 single, \$86 double) is approximately three blocks from the center, easily accessible by the skywalk system.

Hotel reservations must be received by April 16, 1984, to be confirmed. Mail the completed housing form directly to the hotel of your choice. Do not write or telephone AGU for housing reservations.

Scientific Sessions

The program summary appears later in this issue. The preliminary program with the abstracts will be published in the April 17 issue of Eos. The final meeting program, with presentation times, will be distributed at the meeting. Scientific sessions will be held at the Convention-Exposition Center.

Exhibits

Exhibits of instrumentation manufacturers, book publishers, government agencies, and other organizations will run from Tuesday, May 15, to Thursday, May 17, 9 A.M. to 5 P.M. daily.

Special Events

An after-dinner party will be held on Monday evening in the Grand Ballroom of the Clarion Hotel, from 5:30 to 7 P.M. This will be the opening social event of the meeting.

Awards Ceremony and Reception

All meeting participants are invited to attend this event. The Awards Ceremony will be held in the Hall of Mirrors at the Netherland Plaza Hotel at 6:00 P.M. on Wednesday, May 16. A reception in the Third Floor Foyer will immediately follow the ceremony and

offer a time for you to meet, congratulate, and share a glass of wine with those being honored.

President's Dinner

The President's Dinner, held in honor of the medalists, awardees, and Fellows will begin at 8:00 P.M. in the Continental Room of the Netherland Plaza Hotel. Black tie is optional. Dinner tickets are \$25 per person. Purchase tickets with your preregistration because only a limited number will be available for sale at the meeting.

Complimentary refreshments will be served Monday through Thursday at the Convention Center, 9:30 A.M. to 10:30 A.M. and 2:30 P.M. to 3:30 P.M.

Program Summary

Union Approaches to IGBP, Mon PM
Space Research, Tues AM

Atmospheric Sciences
Acid Precipitation, Wed AM
Earth Rotation I, Thurs AM
Upper Atmosphere, Thurs AM
General Meteorology, Thurs PM

Geodesy
Gravity Analysis I, Mon AM
Gravity Analysis I, Mon PM
Precise Positioning: SLR/VLBI, Tues AM
Trends in Geodesy, Tues PM
Geodetic Methods, Wed AM
California Tectonophysics, Wed PM
Geodesy and Tectonophysics, Wed PM
Earth Rotation II, Thurs AM
Earth Rotation II, Thurs PM

Geodynamics
Geodynamics Pgm./CDP, Mon AM
Continental Tectonics I, Mon PM
Gravity Analysis I, Mon PM
Precise Positioning: SLR/VLBI, Tues AM
Crisis Studies, Tues PM
California Tectonics, Tues PM
Geodesy and Tectonophysics, Wed PM
MAGSAT, Wed PM
Earth Rotation I, Thurs AM
Earth Rotation II, Thurs PM
Gravity Analysis II, Thurs AM

AMERICAN GEOPHYSICAL UNION SPRING MEETING MAY 14-18, 1984

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Please Note: Reservations must be received by April 16 in order to be confirmed. All reservations received thereafter will be confirmed subject to availability.

Arrival Date _____ AM ☐ PM ☐

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IMPORTANT NOTE: Hotel MAY require a deposit or some other form of guaranteed arrival. If so, instructions will be on your confirmation form.

The American Geophysical Union Takes Great Pride in Announcing

1984 Medalists and Awardees

Marcel Nicolet — Bowie Medal
Xavier Le Pichon — Ewing Medal
Charles V. Thiels — Horton Medal

1984 Elected Fellows

Samuel J. Bamig, Solar-Planetary Relationships
Subir K. Banerjee, Geomagnetism and Paleomagnetism
Charles A. Barth, Solar-Planetary Relationships/Planetary
Myri E. Beck, Geomagnetism and Paleomagnetism
Christopher H. Chapman, Seismology
Charles C. Counselman III, Geodesy
Russ E. Davis, Ocean Sciences

Jean Francheteau, Tectonophysics
G. Ross Heath, Atmospheric Sciences
Lester Machta, Atmospheric Sciences
Donald R. Neuman, Hydrology
Shomo P. Neuman, Geodesy
Byron D. Tapley, Jr., Volcanology, Geochemistry and Petrology
Hugh P. Taylor, Planetary
John T. Wasson, Volcanology, Geochemistry and Petrology
Donald E. White, Volcanology, Geochemistry and Petrology

All AGU members are cordially invited to attend the prestigious Honors Ceremony. The Ceremony will be Wednesday, May 16, 1984, at 6:00 p.m. in the Hall of Mirrors room of the Netherland Plaza Hotel. A wine reception will immediately follow the presentations. All Spring Meeting participants are invited to attend the Honors Ceremony and Reception. The festivities will continue on with a President's Dinner, held in recognition of the achievements of the medalists, awardees, and elected fellows. Tickets are \$35 per person and will be ordered with your advance registration or purchased at the meeting. Please plan to join us and share in the evening's celebration.

Geomagnetism & Paleomagnetism
Paleomagnetism and Rock Magn., Mon AM
General GP, Mon PM
Magnetic Strat. & Time Scales, Tues AM
MAGSAT, Wed PM
SV & Geodynamic Implications, Thurs AM

Hydrology

General Groundwater I, Mon AM
G-W Transport Field Methods, Mon PM
Transport Processes I, Tues AM
Mesoscale Precipitation I, Tues AM
Transport Processes II, Tues PM
Mesoscale Precipitation II, Tues PM
Calcium Geochemistry, Wed AM
General Groundwater II, Wed AM
General Hydrology, Wed PM
Hillslope Hydrology, Thurs AM
Sediment Storage, Thurs PM

Ocean Sciences

Ocean Drilling, Mon PM
Ocean Response to Winds, Mon PM
Physical Oceanography, Tues AM
EM Fields, Tues PM
Gulf Stream, Tues PM
Straits and Sills, Wed AM
Inland Seas, Wed AM
Pelagic Sedimentation, Wed PM
Gulf of Maine, Wed PM
Marine Chemistry and Geology, Thurs AM
El Niño, Thurs PM

Planetary

Lower Crustal Processes I, Mon AM
Lower Crustal Processes II, Mon PM
Planets and Exospheres, Tues PM
Planetary Posters, Wed AM

Solar

Shallow Structure, Mon AM
Mantle Convection, Mon AM
Rupture and Prediction, Mon PM
Tomography and 3-D Problems, Tues AM
Theoretical Seismology, Tues PM
No. American Earthquakes, Wed AM
Global, Regional, Volcanic, Wed PM
Solid Earth Posters, Wed PM
Honoring Bill Best I, Thurs AM
Structural Seismology II, Thurs PM
Honoring Bill Best II, Thurs PM

SPR: Aeronomy

Aurora-Airglow, Mon AM
Ionosphere-Irregularities, Mon PM

Business Meetings and Section Luncheons

The AGU Council will meet Tuesday, May 15, at 5:30 P.M. The annual business meeting of the Union will follow the Council Meeting. Members are welcome to attend.

All section luncheons will be held at the Clarion Hotel; room locations will be published in the April 17 issue of Eos. Please indicate on the registration form which luncheon you plan to attend and include payment.

Monday, May 14

Geomagnetism and Paleomagnetism, \$7
Keith Runcorn, University of Newcastle, UK, will speak on "Lunar Magnetism."
Sponsor: 2G Enterprises

Planetary/Volcanology, Geochemistry and Petrology, \$9.50

Tuesday, May 15

Seismology, \$5
Lynn R. Sykes, LDGO, will speak on "Seismological Research and the Nuclear Test Ban: The 25th Year." Sponsors: Kinematics, Inc.; Teledyne Industries, Inc.; and W.F. Sprengnether Instruments Co., Inc.

Tectonophysics, \$9.50

Irwin I. Shapiro, Harvard Smithsonian Center for Astrophysics, will speak on "Applications of Space Geodesy to Tectonophysics."

Wednesday, May 16

Hydrology, \$9.50

Ocean Sciences, \$9.50

Paul M. Wolff, NOS/NOAA, will speak on "New Direction for the National Ocean Service."

Solar-Planetary Relationships, \$9.50

S. M. Krimigis, APL/JHU, will speak on "Priorities in Solar and Space Physics: Progress on the Current Academy Study."

Thursday, May 17

Atmospheric Sciences, \$9.50

Geodesy, \$7

Arne Bjerhammar, Visiting Scientist at the National Geodetic Survey, will speak on "Einstein: An Early Surveyor (?)." Sponsor: Bell Aerospace and Textron.

Upper Atmosphere Waves, Tues PM
Thermosphere-Exosphere, Wed AM
Mid-Atmosphere Transport, Wed PM
Ionospheric Processes, Thurs AM
Upper Atmosphere, Thurs AM

SPR: Cosmic Rays

Solar Flare Particles I, Wed AM
Solar Flare Particles II, Wed PM
Cosmic-Ray Cutoff Rigidity, Thurs PM

SPR: Magnetospheric Physics

Comet/Planet Ionospheres, Mon AM
Ionosphere/Plasmaosphere, Mon AM
Project Westford, Mon PM
Auroral Phenomena I, Mon PM
Auroral Phenomena II, Tues PM
Particle Distributions, Tues PM
Numerical Simulations, Tues PM
Jupiter and Saturn, Wed AM
Ionospheric Experiments, Wed AM
Waves/Instabilities I, Wed PM
Reconnection/Pulsations, Thurs AM
Electric Currents/Fields, Thurs AM
Aurora and Substorms, Thurs AM
Disturb Magnetotail, Thurs PM
Waves/Instabilities II, Thurs PM

SPR: Solar & Interplanetary Physics

Solar Wind/Comets, Tues PM
Shocks and Foreshocks, Tues PM
Solar Physics, Thurs AM
Upstream Waves/Particles, Thurs PM

Tectonophysics

Mantle Convection, Mon AM
Continental Tectonics I, Tues PM
Mantle Convection and Processes, Mon PM
Ridges and Fracture Zones, Tues AM
Marine Tectonics, Tues PM
Mineral Point Defects, Tues PM
Crustal Structure, Wed AM
Geodesy and Tectonophysics, Wed PM
Solid Earth Posters, Wed PM
Rocks Deformation, Wed PM
California Tectonics, Wed PM
Continental Extension, Thurs AM
Continental Tectonics II, Thurs AM
Continental Tectonics III, Thurs PM

Volcanology, Geochemistry, & Petrology
Mineral Physics I, Mon AM
Lower Crustal Processes I, Mon AM
Mineral Physics II, Mon PM
Metamorphism and Precambrian, Tues AM
Mineral Physics III, Tues AM
Cumulates and Immiscibility, Tues PM
Mineral Point Defects, Tues PM
Isotopic Geochemistry I, Wed AM
Granite Rocks, Wed AM
Volcanic Petrology, Wed AM
Solid Earth Posters, Wed PM
Oceanic Basalts, Thurs AM
Isotopic Geochemistry II, Thurs AM
Mantle, Thurs PM
Experimental Petrology, Thurs PM

Announcements

TAE Users Conference

May 1-2, 1984. Transportable Applications Executive (TAE) User's Conference, Greenbelt, Md. Sponsor, NASA Goddard Space Flight Center, ITAE Support Office, GSFC Code 933, Greenbelt, MD 20771; tel. 301-344-6034.

This public conference will feature discussion and demonstrations of the Transportable Applications Executive (TAE), a portable, standard computer/user interface which is now available for general use. The TAE program is a command and menu driven system that processes user input and sends it to an application program. It is used by NASA in large-scale meteorological analysis systems, image processing systems, and data base management systems. It is also used by universities and private industry.

The users conference is being planned TAE users, who will offer live demonstrations of the program and low-to sessions on winning applications with TAE, workstation software development with TAE, joining TAE to UNIX, and many other topics.

China and Global Climate

October 30-November 3, 1984. Symposium on Relationships Between Climate of China and Global Climate—Past, Present, and Future, Peking, China. Sponsors, Academia Sinica, IAGAP, American Meteorological Society, Jili-Ping Chao, Institute of Atmospheric Physics, Academia Sinica, Beijing, China.) Deadline for abstracts is May 1, 1984.

The goal of the symposium is to compare climate change in China with that of other regions in the world during the past, present, and future. The physical causes of similarities and differences will be discussed. Among the specific topics to be addressed are climatic fluctuations over the past 2000 years or more, air-sea interactions with particular reference to the west Pacific, land surface-climate interaction, and prediction methods for monthly and seasonal climate variations. The meeting language will be English.

Salt Lakes and Arid Zones

September 24-28, 1984. SLEADS (Salt Lakes, Evaporites, Arid Zones) Workshop on Geozoic Salt Lakes and Arid Zones Hydrology, Geochemistry, Stratigraphy, and Paleoenvironments, Mathoura, New South Wales, Australia. Sponsor, Australian National Univ., J. M. Bowler, Dept. of Biogeography and Geomorphology, Research School of Pacific Studies, Australian National Univ., GPO Box 4, Canberra 2601, Australia.) Registration deadline is May 1.

Contributed papers are invited on the subjects of salt lakes and arid zones, using Australian examples with comparisons from China, Africa, India, and the United States. The conference program will be divided into two general parts: regional, or site specific contributions; and thematic contributions drawing on information from multiple sites.

The meeting will be followed by a 2-day-3

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☐ AMS-American Meteorological Society
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☐ ACSM-American Congress on Surveying and Mapping
☐ CGU-Canadian Geophysical Union
☐ EGU-European Geophysical Union
☐ UGM-Union Geofisica Mexicana

Nonmembers

If you register at the full-meeting rate, the difference between member (or student member) registration and nonmember registration will be applied to AGU dues if a completed membership application is received at AGU by July 9, 1984.

Preregistrants

Your receipt will be in your preregistration packet. The registration fee will be refunded if written notice of cancellation is received in the AGU office by May 7. The program and meeting abstracts will appear in the April 17 issue of Eos, and will be available at the meeting.

AGU 1984 SPRING MEETING

MAY 14-17

Cincinnati, Ohio

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MEMBER	<input type="checkbox"/> \$70	<input type="checkbox"/> \$35
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PRESIDENT'S DINNER (Wednesday Evening)	<input type="checkbox"/> \$25	

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SECTION LUNCHEONS

Circle section and indicate number of tickets. All lunches begin shortly after noon.

_____ Planetary/Volcanology, Geochemistry, and Petrology, Monday, \$9.50
_____ Geomagnetism and Paleomagnetism, Monday, \$7
_____ Seismology, Tuesday, \$5
_____ Tectonophysics, Tuesday, \$9.50
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Meetings (cont. from p. 123)

day excursion through lakes and dunes of the Murray basin. The workshop proceedings are planned for publication. SEADS is a multidisciplinary research project directed toward study of climatic history, present and past hydrology, geomorphology, biology, and geomorphic evolution of late Cenozoic continental arid and semi-arid environments.

The Geophysical Year calendar last appeared in the March 6, 1984, issue.

Meeting Report

Magnetic Reconnection

A Chapman Conference on Magnetic Reconnection was held at the Los Alamos National Laboratory, October 3-7, 1983. More than 125 scientists, from more than a dozen countries, participated in the meeting, where 52 scientific papers were presented and discussed. This report briefly reviews material presented at the conference after first giving some background information on magnetic reconnection.

In many interesting systems of magnetized plasmas, magnetic field lines can be divided into several classes on the basis of their topological properties. One such system is sketched in Figure 1. This represents earth's magnetosphere, enveloped in the flowing solar wind which is threaded by the interplanetary magnetic field (IMF). In this system four classes of field lines are identified: (1) "closed" field lines connected to earth at both ends, (2) "interplanetary" field lines that do not connect to earth at all, (3) "open" field lines connected to earth at one end and to the interplanetary field at the other, and (4) "magnetic loops" that connect neither to earth nor to the interplanetary field. Surfaces called separatrices (heavy lines in Figure 1) separate the regions of different topology (i.e., 2 from 3, 1 from 3, and 1 from 4), and these intersect (or rise upon themselves along lines called X lines) at points A, B, and C in Figure 1.

Figure 1 is adapted from a figure in the classic paper by Dungey (1961), who suggested that magnetic field lines in the flowing solar wind "reconnect" with magnetic field lines of the earth, in the manner shown, and that this process of "magnetic reconnection" accelerates the particles that cause the auroras. The reconnection process involves transporting magnetic flux across separatrices from one region to another, and this is accomplished at the X lines. For example, an interplanetary field line (region 2), brought to the front of the magnetosphere by the solar wind, meets a closed field line (region 1) at A. The two lines break where they touch at A. The line and immediately reconnect to create two open field lines (region 3) that connect to the north and south polar caps of earth. Similarly, two open field lines, reconnecting at C, create an interplanetary field line and a closed field line. A closed field line, reconnecting at B, creates a magnetic loop (region 4) and a shorter closed line.

Both the complexity and the importance of this process arise from the fact that in all cases of physical interest, magnetic field lines are closely coupled to the mechanical behavior of plasma, so topological changes of the magnetic field must include transfer of plasma across separatrices as well. In fact, magnetic reconnection has been defined as the process whereby plasma flows across a surface that separates regions continuing to poloidally different magnetic field lines (Vasyliunas, 1975). Topological changes of field lines thus imply delicate patterns of plasma flow. They result, furthermore, in a conversion of magnetic energy to kinetic energy of the plasma.

The study of reconnection had its origin in

suggestions by Giovanelli (1948, 1947, 1948) and by Hoyle (1949) that charged particles responsible for solar flares and the aurora, respectively, could be accelerated at X type magnetic neutral points. Support for these ideas has been found in ever increasing numbers of theoretical and observational studies during the intervening years. Indeed, today, it is widely believed that magnetic reconnection indeed does explain the sudden large energy releases that characterize solar flares and intense auroral brightenings called auroral or magnetospheric substorms. Furthermore, reconnection has been found to play important roles in several areas of fusion research, and interest in it has arisen in relation to some astrophysical objects.

Despite providing conceptually satisfying explanations for phenomena in a variety of disciplines, the idea of reconnection has faced some skepticism, especially among students of the earth's magnetosphere. Thus, when particularly strong new evidence for reconnection emerged in recent years from satellite observations in the magnetosphere, it seemed appropriate for scientists of various disciplines and interested in reconnection to convene to hear about the new observations and to assess fully our present understanding of the phenomenon. That was the objective of the Los Alamos conference.

The technical program included six topical sessions of invited and contributed papers, one poster session of papers on mixed topics, and a final session on Appraisals, Unsolved Questions, and Future Directions. The six topical sessions treated reconnection theory and modeling and the occurrence of reconnection in the laboratory, in earth's magnetosphere, and in astronomical objects.

Theories and models of reconnection usually consider bodies of plasma that satisfy ideal MHD conditions such that the magnetic field can be considered "frozen" into the plasma, (i.e., moving with it). The actual reconnection of field lines then occurs at a small region of the interface (called the diffusion region) around the X line, where localized breakdown of the frozen field condition occurs. Much discussion at the conference was devoted to examining the extent to which the reconnection process is controlled by external boundary conditions. In one view, favored by Asford, reconnection is controlled by external forces that push differently oriented fields of topologically different regions together and dictate the behavior of the field and plasma around the X line. Models of this process were discussed by Walker and Sato, who refer to it as "driven" reconnection. [This should not be confused with "driven" magnetic substorms, a concept advanced by Alksouf in recent years, in which the reconnection process seems to play no role, or at least not a well-defined one.] In another view, favored, for example, by Schindler, the external effects are considered to push the system to a configuration inherently unstable. Reconnection then is initiated by the instability. In this picture, reconnection plays the decisive role in controlling magnetic topology and in releasing previously stored free energy. Because of its similarity with spontaneous phase transition processes, this picture is often referred to as "spontaneous reconnection." Birn described three-dimensional computer modeling of the magnetotail that portrays such a behavior and that has been highly successful in reproducing magnetic field and flow configurations actually observed during substorms.

Data returned by NASA's ISEE 1 and ISEE 2 satellite pair, launched in 1977, has revolutionized our perception of the process of magnetic reconnection at the magnetopause (e.g., as in Figure 1) and leaves little doubt that reconnection is a significant process for energization of the magnetosphere. Sckelerup summarized the basic aspects of reconnection in the magnetopause setting, including the properties of rotational discontinuities, energization of particles in current layers, and the matter of nonsteady, localized reconnection. Two quite different features in the ISEE data have been interpreted as signatures of magnetopause reconnection, and these have led to the present view that there can be both quasi-steady reconnection and impulsive, small-scale reconnection. Paschmann described the quantitative tests of tangential momentum balance of the plasma and magnetic field across the magnetopause that led to the recognition of quasi-steady state reconnection. Tests of energy balance across the magnetopause were also consistent with the occurrence of reconnection but at a somewhat poorer confidence level. Tracing the magnetic field topology at the magnetopause with energetic particles of magnetospheric origin, as described by Daly, has generally provided consistency checks with the data obtained from momentum balance. The rate and scale size of quasi-steady reconnection, as well as the precise onset conditions, cannot be determined from the ISEE data set. It has been noted, for example, that there have been numerous crossings of the sunward magnetopause when the magnetosheath field was southward (i.e., favorable for magnetopause reconnection as in Figure 1), and signatures of quasi-steady reconnection were, nevertheless, not identified.

The impulsive, small-scale type of reconnection was first recognized in a certain repeating pattern of magnetic variations seen in the magnetosheath just outside the magnetopause. The identification of these as instances of transport of magnetic flux (thus named flux transfer events or FTE's) was described by Russell. The interpretation is that spatially and temporally limited reconnection takes place near the sunward equatorial magnetopause and that the connected flux tube is dragged along the magnetopause by the ongoing magnetosheath plasma. Simultaneous ISEE 1 and ISEE 2 measurements of individual FTE's, described by Saunders, revealed that they have diameters of the order of 1 earth radius, the magnetic flux within them is $\sim 5 \times 10^{16}$ Wb, and the internal field is twisted, implying field-aligned currents of a few times 10^6 A. Rijnbeek and Berchem reported that FTE's are seen very frequently (every few minutes) by a satellite located near the sunward magnetopause where the IMF is southward.

Figure 1 shows two X lines in the magnetotail at locations B and C. That at A is sometimes referred to as the "distant neutral line" or the "quiet time neutral line." It is thought to be located ~ 100 to $200 R_E$ from earth and to be present most of the time, letting plasma and closed field lines earthward to maintain the plasma sheet of closed field lines (region 1). The leading substorm theory, often referred to as the neutral line model, or the reconnection model, holds that at the onset of a substorm's expansive phase (marked by sudden intense brightening of polar aurora) a "near-earth neutral line" or "substorm neutral line" forms at B. This follows a preliminary interval (growth phase) of ~ 30 to 60 min during which magnetic energy (i.e., mag-

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netic field lines) is being added to the magnetotail by reconnection with the IMF at A (Figure 1), leading to a stronger more radial field. Reconnection at B soon (in a few minutes) severs the plasma sheet (transforming it into a system of closed loops (i.e., region 4) and a system of open field lines (i.e., region 3) that connect to earth at one end and to the interplanetary field at the other. This "plasma sheet" completely detached from the earth, it is carried tailward, eventually to be joined by the solar wind. Briefly, the model is characterized by a period (growth phase) of magnetic field expansion by interplanetary magnetic field (IMF) reconnection at the magnetopause, followed by a spontaneous brightening period (expansion phase) of "unloading" energy during which the tail energy content decreases. The conference session on reconnection in the magnetotail reviewed the observations around which this model has been built, raised against reconnection by students of the magnetosphere has been directed against the above reconnection model of substorms. Opening the conference session on reconnection in the magnetotail, Nishida critically reviewed the evidence and observational bases for the model, concluding that the model is not yet fully understood and that it is probably not the only important agent of tail plasma dynamics. Confusion and skepticism have arisen when people have tried to explain every dynamical feature as due to reconnection and, failing to do so, have discovered the connection model altogether. The evidence

for the onset of reconnection at expansive phase onset and the ensuing formation and departure of a plasmoid lies in observations, in the tail, of tailward plasma flow, southward turning of the magnetic field, tailward streaming of energetic electrons, and plasma sheet dropout. Bieber reviewed these observations, and Nishida reported on electric field measurements, made by ISEE 1, that have also been recently added to the overall observation set that supports this picture of plasmoid formation and the neutral line model in general. The stretching and intensity increase of the tail field, which are two of the manifestations of tail energization during the growth phase, were described by Fairfield and D. N. Baker, as were observations indicating the loss of tail energy during expansive phase onset. Both speakers also demonstrated that the growth of tail energy (growth phase) starts a few minutes after the IMF turns southward.

There is much observational evidence that energetic (up to ~ 1 MeV) protons and electrons are generated in the magnetosphere during substorms. They are seen in the magnetotail, and they are "injected" into the inner magnetosphere where they are observed as geosynchronous orbits ($r \approx 6.6 R_E$ in conjunction with essentially every substorm). D. N. Baker discussed the energetic ion "drift echoes" observed at $6.6 R_E$ and the "impulsive bursts" of ions seen in the magnetotail, both phenomena suggesting that the energization generation may be temporally confined to an interval of a few minutes around expansive phase onset. Scholer presented a general review of the extensive observations of energetic ions and electrons in the magnetosphere and noted that there have been comparatively few theoretical studies to explain them. Asford suggested that the particles may be accelerated as the plasma sheet is severed since magnetic reconnection may occur very rapidly then and cross-tail potentials as high as ~ 1 MeV might be expected to exist briefly.

NASA's ISEE 3 satellite made passes through the magnetotail as far as $220 R_E$ from earth during 1982-1983, and several reports of those observations were presented at the conference. These reports contained dramatic new evidence supporting reconnection models of the magnetosphere in general and of substorms in particular. ISEE 3 found that the characteristic cross-sectional structure of the tail (i.e., north and south lobes, separated by a plasma sheet) was recognizable at all distances examined. The flow of plasma in the plasma sheet was almost always tailward and fast beyond $\sim 100 R_E$. Scholer and Daly reported that the plasma sheet also contains tailward streaming energetic electrons and ions and that these actually extend above and below the plasma sheet. Cowley showed that all these features are consistent with an open magnetosphere with reconnection occurring at a neutral line earthward of ISEE 3. Cowling reported that the lobe plasma density is often quite different on opposite sides of the plasma sheet and found that these differences showed a dependence on the IMF y component that is consistent with reconnection of the IMF with earth's field near the subsolar

magnetopause. D. N. Baker reported increases of the tail diameter at ISEE 3 concurrent with growth phase signatures at geosynchronous orbit and with southward IMF, supporting the picture of tail energization before substorm expansion phases. Hones, Siscoe, and Scholer reported the occurrence of fast tailward moving plasma structures which they identified as plasmoids (i.e., severed plasma sheet sections) reaching ISEE 3 about 30 min after expansive phase onset at earth (a delay appropriate for the earth-ISEE distance and the 500-1000 km/s flow speed measured in the passing plasmoids).

It is reasonable to expect that magnetic reconnection occurs in other magnetospheres as well as that of earth. Indeed, Behannon and Nishida reported observations of Jovian magnetotail fields and plasmas that can be interpreted as resulting from reconnection in Jupiter's magnetosphere. Niedner discussed comet tail disconnection events (DE's) that have been ascribed to magnetic reconnection at the comet's head when the polarity of the field draping the comet is reversed at IMF sector boundaries. A few examples have been found of discontinuities in comet tail structure that may be due to tail reconnection, similar to the substorm process at earth. Priest reported that our understanding of the sun's atmosphere has changed dramatically over the past 10 years. Our new view of the sun is dominated by the magnetic field and its relation with the plasma atmosphere in which magnetic reconnection plays a prime role. For example, the solar corona may be heated by turbulent reconnection, and reconnection may play several roles in solar flares. Parker stated that a universal feature of magnetized plasmas is its activity (i.e., plasma turbulence and waves, shocks, superheated gases, and the production of fast particles) which occurs whenever and wherever a magnetic field in a tenuous plasma is subject to externally imposed strains. He also proposed that magnetic reconnection may be the central cause of the activity.

In the laboratory, several axisymmetric toroidal magnetic confinement experiments are presently being studied for controlled fusion. Magnetic reconnection plays a role in at least four of these. The tokamaks is presently the leading contender for development into a fusion power reactor, and in it the role of reconnection is detrimental to plasma confinement. Paré discussed reconnection in tokamak and demonstrated its occurrence in the ISX-B device at the Oak Ridge National Laboratory. In the reversed-field pinch (RFP) experiment, both toroidal and poloidal magnetic fields are externally applied and are of comparable intensity, resulting in a very highly sheared field unlike that of the tokamak where the toroidal field (aligned the long way around the torus) everywhere dominates the poloidal field (aligned the short way around). D. A. Baker reported that the Los Alamos ZT-40M experiment has unambiguously demonstrated constant current and reversed field for 10 ms (much longer than predicted by calculations) possibly by energy transfer from the poloidal field to the toroidal field by steady state reconnection of the mean fields.

The Field Reversed Configuration (FRC) and the spheromak were discussed by Milroy and by Hammer, respectively. These devices are members of the "Compact Torus" family of magnetic structures characterized by a set of closed, nested flux surfaces but without any coils, transformer cores, etc., protruding through the hole in the torus. Their magnetic configurations are shown in Figure 2. The formation of both involves magnetic reconnection. Spheromaks have been formed successfully in several different ways. In each case, during a "preformation stage," poloidal field lines are wrapped around (or penetrate) solid bodies. During formation, plasma is created, and the toroidal component of the field is introduced. Magnetic forces cause the flux surfaces to distort and eventually reconnect to form the desired set of closed, nested surfaces sketched at the top of Figure 2. FRC's are formed in a field-reversed 8-pinch as follows: (1) an initial reverse bias field is frozen into a cold pre-ionized plasma; (2) the current in the 8-pinch coil is quickly reversed, producing a large forward bias field, which causes the plasma to implode radially; (3) the oppositely directed field lines reconnect near the 8-pinch ends forming a closed field configuration such as is sketched at the bottom of Figure 2.

In summary, the conference exposed many interested scientists to discussions of present thinking about magnetic reconnection and to descriptions of the latest developments concerning reconnection in space and laboratory plasmas. Most of the formal presentations as well as the discussion of them by the participants will appear in the AGU *Geophysical Research Letters*, vol. 30, *Magnetic Reconnection in Space and Laboratory Plasmas*, to be available at the 1984 AGU Spring Meeting in Cincinnati.

Cosponsors of the conference, along with the American Geophysical Union and Los Alamos National Laboratory, were the U.S. Department of Energy, the Institute of Geophysics and Planetary Physics of the University of California, NASA, and the National Science Foundation.

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This meeting report was contributed by Edward W. Hones, Jr., University of California, Los Angeles National Laboratory, Los Angeles, CA 90024.

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This meeting report was contributed by Edward W. Hones, Jr., University of California, Los Angeles National Laboratory, Los Angeles, CA 90024.

Travel Funds to Spring Meeting Available to Foreign Graduate Students

Grants of up to \$250 are available to foreign graduate students studying in the U.S. for travel to the AGU Spring Meeting, May 14-18 in Cincinnati, Ohio.

The funds, a grant from the Short-Term Enrichment Program (STEP) of the U.S. Information Agency, are available to full-time foreign graduate students who are not receiving ANY U.S. government funds. Students in refugee, immigrant or tourist visa status are not eligible.

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Hiring, Firing, and Job Security

AGU Spring Meeting
Tuesday, May 15
5:15 - 7:15 P.M.
Ivory B Room • The Clarion

This panel discussion of current practices in employment of geophysicists in a wide range of areas (academia, industry and government) will include who gets hired, how to stay hired and possibilities of firing, as seen from the employer's point of view. Laurie Brown, Visiting Associate Professor, Department of Geoscience, New Mexico Institute of Mining and Technology, will moderate the discussion.

This Program has been arranged by the AGU Education and Human Resources Committee. Refreshments will be available.

recognition is introduced into both forward and inverse computer algorithms used in the study of seismicity. A given degree is also under the influence of a typical layer. *Geophysics*, vol. 49, no. 5.

0930 Seismic methods
ANALYSIS OF PLATE DIFFERENCES APP. FIFTEEN-SEVENTEEN
MODELS OF THE SCALAR AND VECTOR VARIATIONS
S. J. Haxby, Lamont-Doherty Earth Observatory, P.O. Box 591,
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Aeronomy

0410 Observation and Scattering of Radiation
PHOTON SCATTERING OF RADIATION
A. J. S. Smith (Department of Physics, University of
Melbourne, Australia), S. J. Haxby (Lamont-Doherty Earth
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Electromagnetics

0750 Electromagnetic Energy Transfer
ELECTROMAGNETIC ENERGY TRANSFER
A. J. S. Smith (Department of Physics, University of
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Exploration Geophysics

0810 Computer applications
COMPUTER APPLICATIONS
A. J. S. Smith (Department of Physics, University of
Melbourne, Australia), S. J. Haxby (Lamont-Doherty Earth
Observatory, Palisades, NY 10962), S. J. Haxby (Lamont-Doherty
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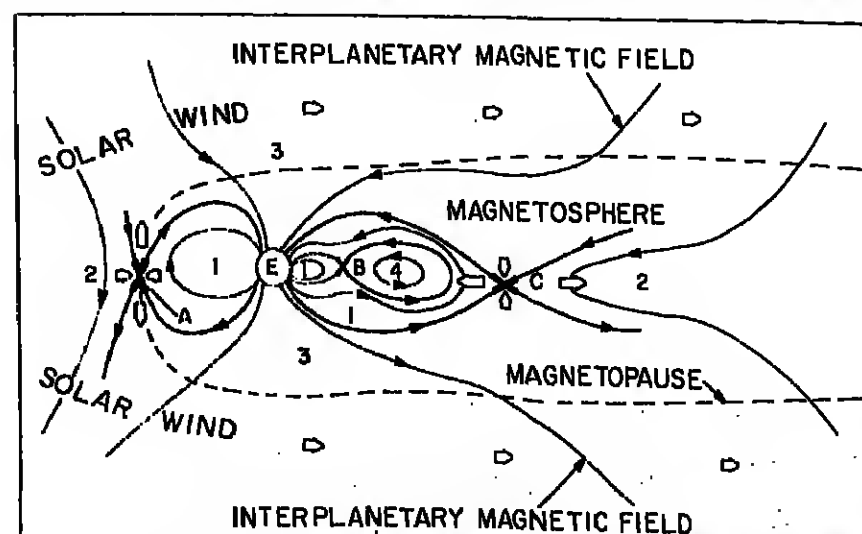


Fig. 1. A sketch of the solar wind-magnetosphere plasma system. Black lines are magnetic field lines with arrows indicating their direction. White arrows indicate plasma bulk flow. The dashed line is the magnetopause, the boundary between the solar wind-dominated regime and the earth-dominated regime. The drawing is not to scale. Actual distances are earth (E) to A ≈ 10 earth radii (RE) (1 RE = 6370 km); E to B ≈ 15 RE; E to C ≈ 100 RE; magnetotail diameter ~ 40 RE.

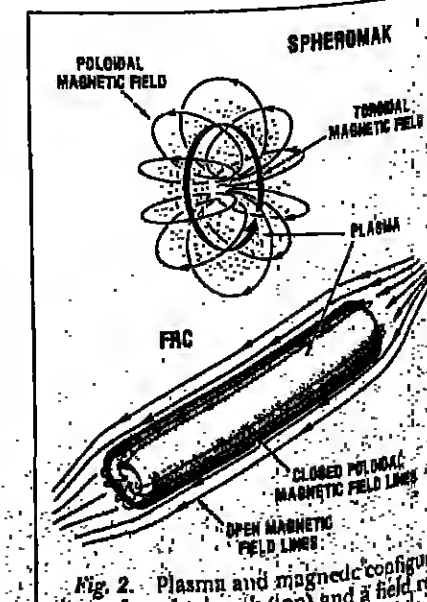


Fig. 2. Plasma and magnetic configurations of a spheromak (top) and a field-reversed configuration (bottom).

